Huge Graph Analysis on Your **Own Server with WebGraph in** Rust

Tommaso Fontana, Sebastiano Vigna, Stefano Zacchiroli

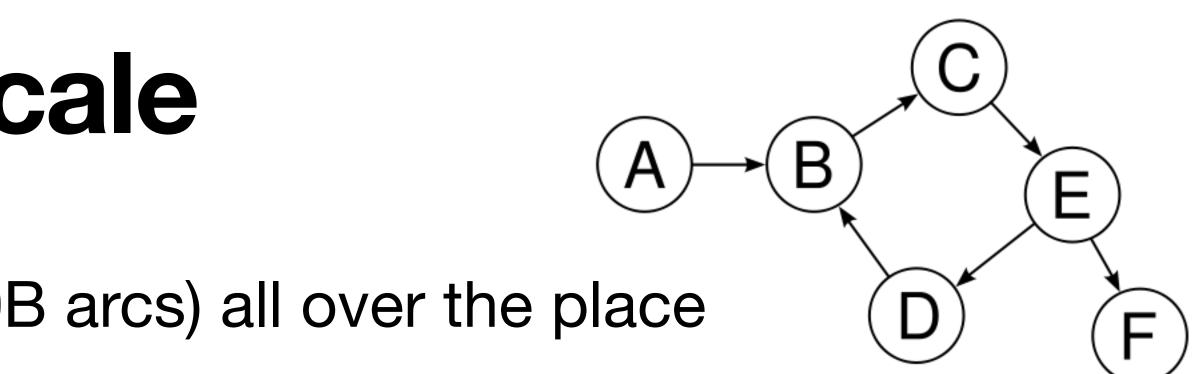
Michele Andreata, Lorenzo Cimini, Davide Cologni, Matteo Dell'Acqua, Dario Moschetti, Valentin Tablan, Matteo Zagheno

Partially supported by project SERICS (PE00000014) under the NRRP MUR program funded by the EU - NGEU, and by project ANR COREGRAPHIE, grant ANR-20-CE23-0002 of the French Agence Nationale de la Recherche

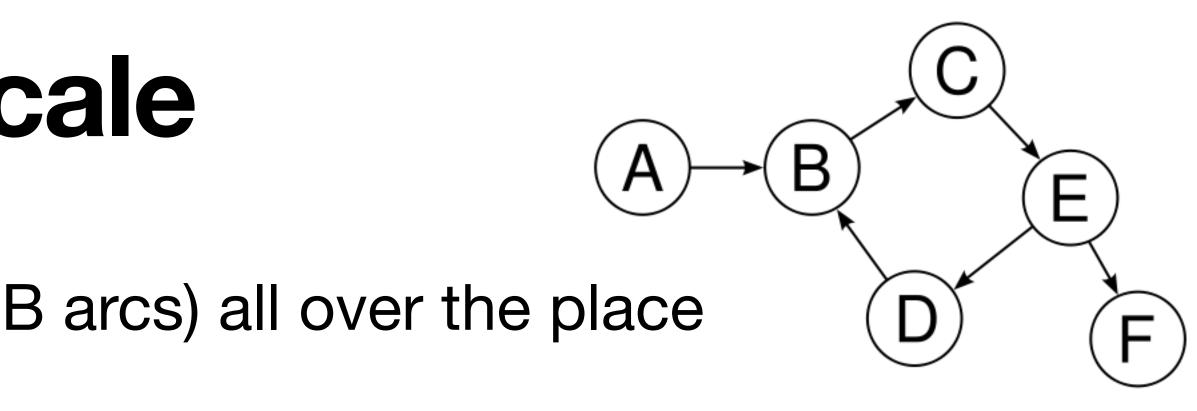


• Today we found huge graphs (>100B arcs) all over the place

• Today we found huge graphs (>100B arcs) all over the place

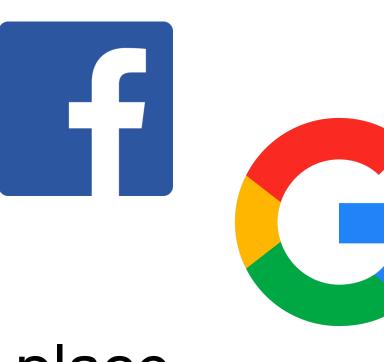


- Today we found huge graphs (>100B arcs) all over the place
- Web snapshots, social networks, biological graphs, ...



- Today we found huge graphs (>100B arcs) all over the place
- Web snapshots, social networks, biological graphs, ...

- Today we found huge graphs (>100B arcs) all over the place
- Web snapshots, social networks, biological graphs, ...



- Today we found huge graphs (>100B arcs) all over the place
- Web snapshots, social networks, biological graphs, …
- Very large graphs require new approaches





- Today we found huge graphs (>100B arcs) all over the place
- Web snapshots, social networks, biological graphs, ...
- Very large graphs require new approaches
- Standard representations in main memory are either impossible (graph too large) or very expensive (many TB of core memory)



- Today we found huge graphs (>100B arcs) all over the place
- Web snapshots, social networks, biological graphs, ...
- Very large graphs require new approaches
- Standard representations in main memory are either impossible (graph too large) or very expensive (many TB of core memory)
- Distributed approaches spend a very large amount of time distributing data among nodes



- Today we found huge graphs (>100B arcs) all over the place
- Web snapshots, social networks, biological graphs, ...
- Very large graphs require new approaches
- Standard representations in main memory are either impossible (graph too large) or very expensive (many TB of core memory)
- Distributed approaches spend a very large amount of time distributing data among nodes
- What can we do? Compression!



• An open source framework for compressed representation of graphs

- An open source framework for compressed representation of graphs
- One of the most long-lived projects of this kind (>20 years!)

- An <u>open source framework</u> for compressed representation of graphs
- One of the most long-lived projects of this kind (>20 years!)
- Hundreds of publications in major conferences and journals using it (>1500 references)

- An open source framework for compressed representation of graphs
- One of the most long-lived projects of this kind (>20 years!)
- Hundreds of publications in major conferences and journals using it (>1500 references)
- In 2011 news went around the world: Facebook had four degrees of separation

- An open source framework for compressed representation of graphs
- One of the most long-lived projects of this kind (>20 years!)
- Hundreds of publications in major conferences and journals using it (>1500) references)
- In 2011 news went around the world: Fac separation







- An open source framework for compressed representation of graphs
- One of the most long-lived projects of this kind (>20 years!)
- Hundreds of publications in major conferences and journals using it (>1500 references)
- In 2011 news went around the world: Facebook had four degrees of separation

- An <u>open source framework</u> for compressed representation of graphs
- One of the most long-lived projects of this kind (>20 years!)
- Hundreds of publications in major conferences and journals using it (>1500 references)
- In 2011 news went around the world: Facebook had four degrees of separation
- The measurement was performed at Facebook in collaboration with our group using WebGraph (at that time, 721M nodes, 69B links, just 211GB!)

- An <u>open source framework</u> for compressed representation of graphs
- One of the most long-lived projects of this kind (>20 years!)
- Hundreds of publications in major conferences and journals using it (>1500 references)
- In 2011 news went around the world: Facebook had four degrees of separation
- The measurement was performed at Facebook in collaboration with our group using WebGraph (at that time, 721M nodes, 69B links, just 211GB!)
- <u>Common Crawl</u> distributes data using WebGraph





The largest public archive of public and git-style version control history •





- The largest public archive of public and git-style version control history
- Data model: a Merkle direct acyclic graph (intuitively: a single git repository with the development history of all public code)





- The largest public archive of public and git-style version control history
- Data model: a Merkle direct acyclic graph (intuitively: a single git repository with the \bullet development history of all public code)
- One of the largest graphs of human activity available





- The largest public archive of public and git-style version control history
- Data model: a Merkle direct acyclic graph (intuitively: a single git repository with the development history of all public code)
- One of the largest graphs of human activity available
- 44 billion nodes, 769 billion arcs (December 2024), represented by WebGraph in 251GB instead of >6TB!





- The largest public archive of public and git-style version control history
- Data model: a Merkle direct acyclic graph (intuitively: a single git repository with the development history of all public code)
- One of the largest graphs of human activity available
- 44 billion nodes, 769 billion arcs (December 2024), represented by WebGraph in 251GB instead of >6TB!
- The previous Java WebGraph-based pipeline for graph analytics was born out of a collaboration between Inria and the Università degli Studi di Milano





- The largest public archive of public and git-style version control history
- Data model: a Merkle direct acyclic graph (intuitively: a single git repository with the development history of all public code)
- One of the largest graphs of human activity available
- 44 billion nodes, 769 billion arcs (December 2024), represented by WebGraph in 251GB instead of >6TB!
- The previous Java WebGraph-based pipeline for graph analytics was born out of a collaboration between Inria and the Università degli Studi di Milano
- Storing explicitly the graph makes it possible to perform provenance analysis, plagiarism detection, clone detection, etc., at an unprecedented scale

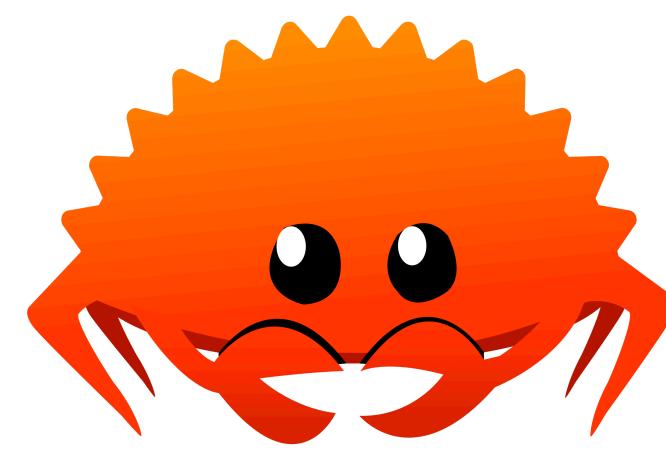




- The largest public archive of public and git-style version control history
- Data model: a Merkle direct acyclic graph (intuitively: a single git repository with the development history of all public code)
- One of the largest graphs of human activity available
- 44 billion nodes, 769 billion arcs (December 2024), represented by WebGraph in 251GB instead of >6TB!
- The previous Java WebGraph-based pipeline for graph analytics was born out of a collaboration between Inria and the Università degli Studi di Milano
- Storing explicitly the graph makes it possible to perform provenance analysis, plagiarism detection, clone detection, etc., at an unprecedented scale
- Still, Java started to get in the way

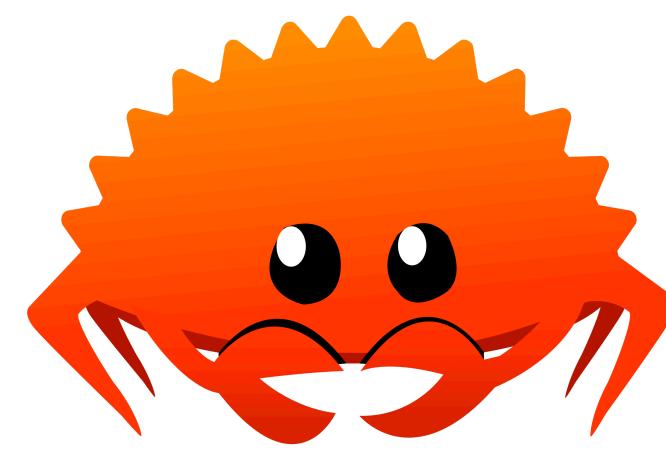






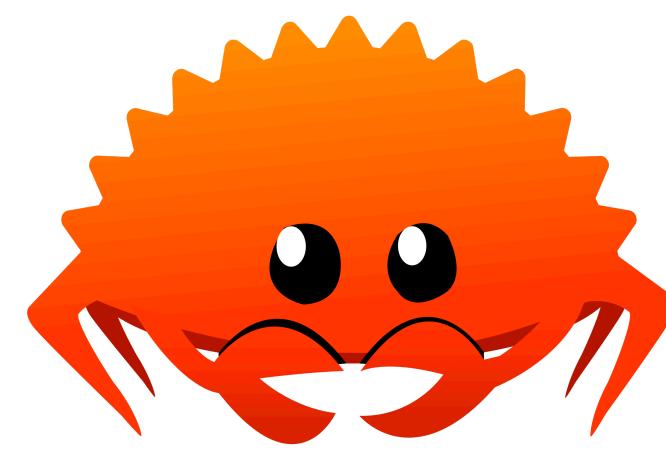


• A high-performance, safe language



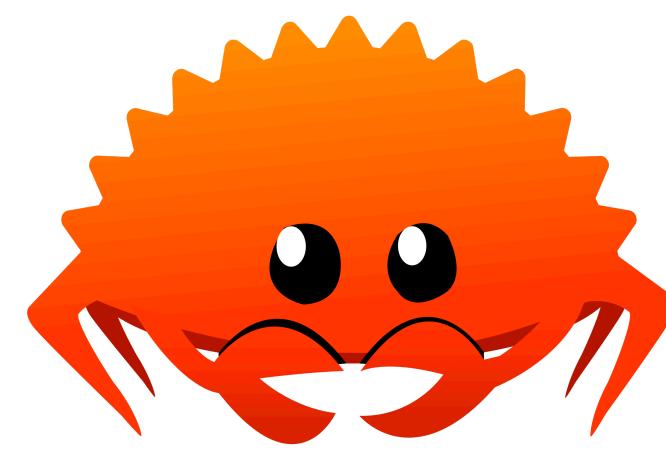


- A high-performance, safe language
- Zero-cost abstractions





- A high-performance, safe language
- Zero-cost abstractions
- Arrays as large as memory allows





- A high-performance, safe language
- Zero-cost abstractions
- Arrays as large as memory allows
- Fine-grained access to OS facilities (memory mapping)





- A high-performance, safe language
- Zero-cost abstractions
- Arrays as large as memory allows
- Fine-grained access to OS facilities (memory mapping)
- Lazy iterators





- A high-performance, safe language
- Zero-cost abstractions
- Arrays as large as memory allows
- Fine-grained access to OS facilities (memory mapping)
- Lazy iterators
- Moving to Rust required porting or rethinking several key ideas







ε-serde (epserde): ε-copy serialization/deserialization

- ε-serde (<u>epserde</u>): ε-copy serialization/deserialization
- <u>mem dbg</u>: fast memory footprint analysis

- ε-serde (epserde): ε-copy serialization/deserialization
- <u>mem_dbg</u>: fast memory footprint analysis
- sux: succinct data structures

- ε-serde (epserde): ε-copy serialization/deserialization
- <u>mem dbg</u>: fast memory footprint analysis
- sux: succinct data structures
- <u>dsi-bitstream</u>: fast bit streams with support for several types of instantaneous codes

- ε-serde (<u>epserde</u>): ε-copy serialization/deserialization
- <u>mem dbg</u>: fast memory footprint analysis
- sux: succinct data structures
- <u>dsi-bitstream</u>: fast bit streams with support for several types of instantaneous codes
- <u>dsi-progress-logger</u>: time-based (concurrent) progress logger

- ε-serde (<u>epserde</u>): ε-copy serialization/deserialization
- <u>mem dbg</u>: fast memory footprint analysis
- sux: succinct data structures
- <u>dsi-bitstream</u>: fast bit streams with support for several types of instantaneous codes
- <u>dsi-progress-logger</u>: time-based (concurrent) progress logger
- ...and, of course, <u>webgraph</u>

ε-copy serialization and deserialization

- ε-copy serialization and deserialization

• Like zero-copy, without the limitations (and, of course, with other limitations)

- ε-copy serialization and deserialization
- Like zero-copy, without the limitations (and, of course, with other limitations) • Unlike abomonation, it does not change the memory (e.g., you can map
- immutable files into memory)

- ε-copy serialization and deserialization
- Like zero-copy, without the limitations (and, of course, with other limitations) • Unlike abomonation, it does not change the memory (e.g., you can map
- immutable files into memory)
- Unlike Zerovec, no impact on performance, and you use standard structures

- ε-copy serialization and deserialization
- Like zero-copy, without the limitations (and, of course, with other limitations) • Unlike abomonation, it does not change the memory (e.g., you can map
- immutable files into memory)
- Unlike Zerovec, no impact on performance, and you use standard structures
- Unlike rkiv, the structure you deserialize is the structure you serialize, and no impact on performance

- ε-copy serialization and deserialization
- Like zero-copy, without the limitations (and, of course, with other limitations) • Unlike abomonation, it does not change the memory (e.g., you can map
- immutable files into memory)
- Unlike Zerovec, no impact on performance, and you use standard structures
- Unlike rkiv, the structure you deserialize is the structure you serialize, and no impact on performance
- Requires collaboration from the underlying struct: the types you want to εcopy must be type parameters

Types are zero-copy (ZeroCopy trait) or deep-copy (DeepCopy trait)

- Types are zero-copy (ZeroCopy trait) or deep-copy (DeepCopy trait)
- references to slices, without any copying

• Sequences (vectors, boxed slices, etc.) of zero-copy types are replaced by

- Types are zero-copy (ZeroCopy trait) or deep-copy (DeepCopy trait)
- Sequences (vectors, boxed slices, etc.) of zero-copy types are replaced by references to slices, without any copying
- The rest of the structure, usually a small (ε-) fraction of the space occupancy, is allocated normally

- Types are zero-copy (ZeroCopy trait) or deep-copy (DeepCopy trait)
- Sequences (vectors, boxed slices, etc.) of zero-copy types are replaced by references to slices, without any copying
- The rest of the structure, usually a small (ε-) fraction of the space occupancy, is allocated normally
- We use disjoint trait implementation based on an associated type to make the framework behave in a different way for zero-copy and deep-copy types

- Types are zero-copy (ZeroCopy trait) or deep-copy (DeepCopy trait)
- Sequences (vectors, boxed slices, etc.) of zero-copy types are replaced by references to slices, without any copying
- The rest of the structure, usually a small (ε-) fraction of the space occupancy, is allocated normally
- We use disjoint trait implementation based on an associated type to make the framework behave in a different way for zero-copy and deep-copy types
- After deserialization you get a structure containing references to the original memory, and you need to pack it in a MemCase if you need to move it around

- Types are zero-copy (ZeroCopy trait) or deep-copy (DeepCopy trait)
- Sequences (vectors, boxed slices, etc.) of zero-copy types are replaced by references to slices, without any copying
- The rest of the structure, usually a small (ε-) fraction of the space occupancy, is allocated normally
- We use disjoint trait implementation based on an associated type to make the framework behave in a different way for zero-copy and deep-copy types
- After deserialization you get a structure containing references to the original memory, and you need to pack it in a MemCase if you need to move it around
- You cannot have references in the structure

PR #1672 RustyYato trick

PR #1672 RustyYato trick

pub struct Zero {} pub struct Deep {}

pub trait CopyType: Sized { type Copy;

}

PR #1672 RustyYato trick pub struct Zero {} pub struct Deep {} pub trait CopyType: Sized { type Copy; }

- pub trait ZeroCopy: CopyType<Copy = Zero> {}
- impl<T: CopyType<Copy = Zero>> ZeroCopy for T {}
- pub trait DeepCopy: CopyType<Copy = Deep> {}
- impl<T: CopyType<Copy = Deep>> DeepCopy for T {}

PR #1672 RustyYato trick

pub struct Zero {} pub struct Deep {} pub trait CopyType: Sized { type Copy; }

- pub trait ZeroCopy: CopyType<Copy = Zero> {}
- impl<T: CopyType<Copy = Zero>> ZeroCopy for T {}
- pub trait DeepCopy: CopyType<Copy = Deep> {}
- impl<T: CopyType<Copy = Deep>> DeepCopy for T {}
- // This is not possible directly--you need a helper struct and T: CopyType<Copy = Zero/Deep> impl<T: ZeroCopy> Deserialize for T { ... } impl<T: DeepCopy> Deserialize for T { ... }



#[derive(Epserde, Debug, PartialEq)] struct MyStruct<A> { **Example** data: A, }

```
#[derive(Epserde, Debug, PartialEq)]
struct MyStruct<A> {
    id: isize,
    data: A,
}
// Create a structure where A is a Vec<isize>
let s: MyStruct<Vec<isize>> = MyStruct { id: 0, data: vec![0, 1, 2, 3] };
// Serialize it
let mut file = std::env::temp_dir();
file.push("serialized");
s.store(&file);
```

```
#[derive(Epserde, Debug, PartialEq)]
struct MyStruct<A> {
    id: isize,
    data: A,
}
// Create a structure where A is a Vec<isize>
let s: MyStruct<Vec<isize>> = MyStruct { id: 0, data: vec![0, 1, 2, 3] };
// Serialize it
let mut file = std::env::temp_dir();
file.push("serialized");
s.store(&file);
// Load the serialized form in a buffer
let b = std::fs::read(&file)?;
```

```
#[derive(Epserde, Debug, PartialEq)]
struct MyStruct<A> {
    id: isize,
    data: A,
}
// Create a structure where A is a Vec<isize>
let s: MyStruct<Vec<isize>> = MyStruct { id: 0, data: vec![0, 1, 2, 3] };
// Serialize it
let mut file = std::env::temp_dir();
file.push("serialized");
s.store(&file);
// Load the serialized form in a buffer
let b = std::fs::read(&file)?;
// The type of t will be inferred--it is shown here only for clarity
let t: MyStruct<&[isize]> =
    <<u>MyStruct</u><<u>Vec</u><<u>isize</u>>>>::deserialize_eps(b.as_ref())?;</u>
```

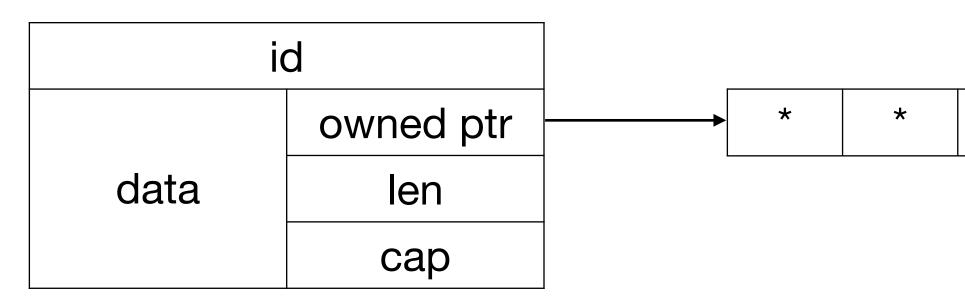
```
#[derive(Epserde, Debug, PartialEq)]
struct MyStruct<A> {
    id: isize,
    data: A,
}
// Create a structure where A is a Vec<isize>
let s: MyStruct<Vec<isize>> = MyStruct { id: 0, data: vec![0, 1, 2, 3] };
// Serialize it
let mut file = std::env::temp_dir();
file.push("serialized");
s.store(&file);
// Load the serialized form in a buffer
let b = std::fs::read(&file)?;
// The type of t will be inferred--it is shown here only for clarity
let t: MyStruct<&[isize]> =
    <<u>MyStruct</u><<u>Vec</u><<u>isize</u>>>>::deserialize_eps(b.as_ref())?;</u>
// This is a traditional deservalization instead
let t: MyStruct<Vec<isize>> =
    <<u>MyStruct</u><<u>Vec</u><<u>isize</u>>>>::load_full(&file)?;
```

```
#[derive(Epserde, Debug, PartialEq)]
struct MyStruct<A> {
    id: isize,
    data: A,
}
// Create a structure where A is a Vec<isize>
let s: MyStruct<Vec<isize>> = MyStruct { id: 0, data: vec![0, 1, 2, 3] };
// Serialize it
let mut file = std::env::temp_dir();
file.push("serialized");
s.store(&file);
// Load the serialized form in a buffer
let b = std::fs::read(&file)?;
// The type of t will be inferred--it is shown here only for clarity
let t: MyStruct<&[isize]> =
    <<u>MyStruct</u><<u>Vec</u><<u>isize</u>>>>::deserialize_eps(b.as_ref())?;</u>
// This is a traditional deservalization instead
let t: MyStruct<Vec<isize>> =
    <<u>MyStruct</u><<u>Vec</u><<u>isize</u>>>>::load_full(&file)?;
// In this case we map the data structure into memory
let u: MemCase<MyStruct<&[isize]>> =
    <<u>MyStruct</u><<u>Vec</u><<u>isize</u>>>>::mmap(&file, Flags::empty())?;</u>
```





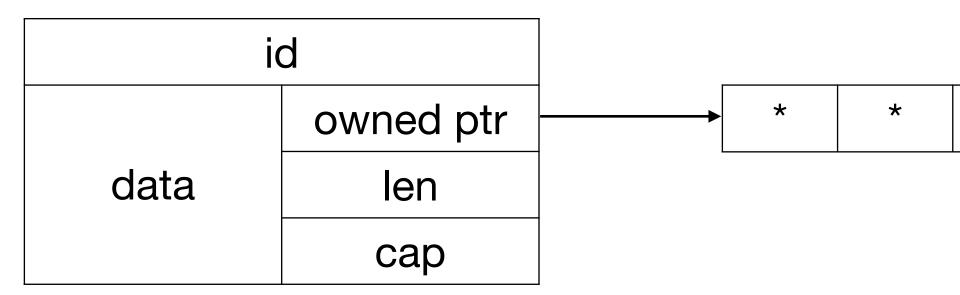
Construction time



*	*	*	*	*	*	*	*



Construction time



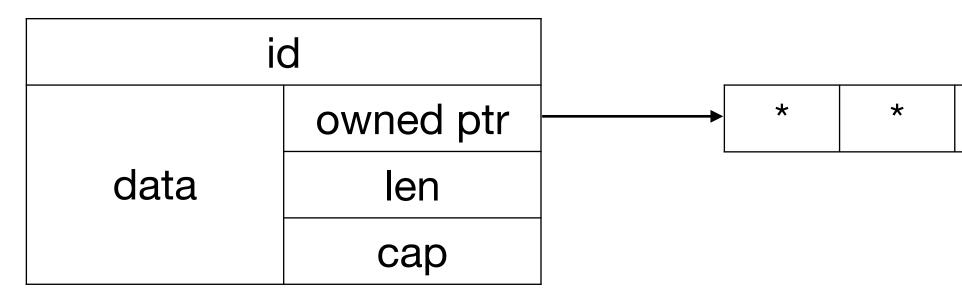
Serialized

id	len	*	*	*	*	*	*	*	*
----	-----	---	---	---	---	---	---	---	---

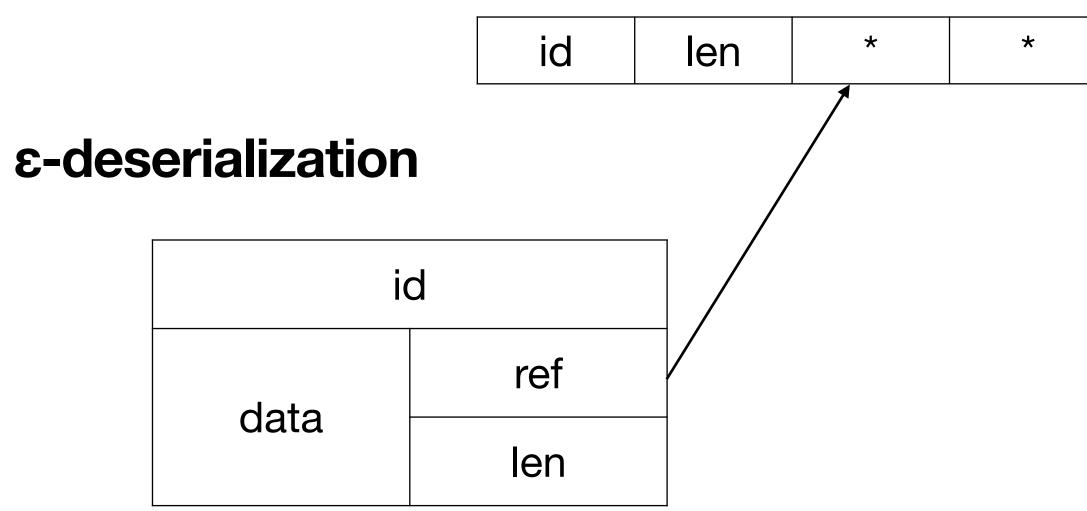
*	*	*	*	*	*	*	*



Construction time



Serialized



*	*	*	*	*	*	*	*

*	*	*	*	*	*

the ε-deserialized structure

• In the previous example, you are supposed to write all read-only methods for MyStruct using AsRef<&[isize]> as the type parameter: then they will work on

- the ε-deserialized structure
- will be ε -deserialized recursively

• In the previous example, you are supposed to write all read-only methods for MyStruct using AsRef<&[isize]> as the type parameter: then they will work on

Structures supporting ε-serde can be just used as a type parameter and they

- the ε-deserialized structure
- will be ε -deserialized recursively
- which can become a nuisance

• In the previous example, you are supposed to write all read-only methods for MyStruct using AsRef<&[isize]> as the type parameter: then they will work on

Structures supporting ε-serde can be just used as a type parameter and they

• If you have several different such fields, you'll have as many type parameters,

- the ε-deserialized structure
- will be ε -deserialized recursively
- which can become a nuisance
- be zero-copied)

• In the previous example, you are supposed to write all read-only methods for MyStruct using AsRef<&[isize]> as the type parameter: then they will work on

Structures supporting ε-serde can be just used as a type parameter and they

• If you have several different such fields, you'll have as many type parameters,

• If you think of your structure as a tree, only leaves reachable through a path of ε-serde-supporting type parameters will be zero-copied (given that they can

• High-performance memory-occupancy detector

- High-performance memory-occupancy detector

Leverages on ε-serde's notion of zero-copy data to avoid iterating on collections

- High-performance memory-occupancy detector

Allocated:	2281701509	
get_size:	1879048240	152477833 ns
deep_size_of:	1879048240	152482000 ns
size_of:	2281701432	152261958 ns
mem_size:	2281701424	209 ns

Leverages on *ɛ*-serde's notion of zero-copy data to avoid iterating on collections

- High-performance memory-occupancy detector

Allocated:	2281701509	
get_size:	1879048240	152477833 ns
deep_size_of:	1879048240	152482000 ns
size_of:	2281701432	152261958 ns
mem_size:	2281701424	209 ns

Additionally, prints memory layouts, including padding

Leverages on *\varepsilon* -serde's notion of zero-copy data to avoid iterating on collections

- High-performance memory-occupancy detector

Allocated:	2281701509	
get_size:	1879048240	152477833 ns
deep_size_of:	1879048240	152482000 ns
size_of:	2281701432	152261958 ns
mem_size:	2281701424	209 ns

- Additionally, prints memory layouts, including padding

Leverages on *ɛ*-serde's notion of zero-copy data to avoid iterating on collections

By using the nightly offset_of_enum feature we can also display padding in enums

- High-1.207 kB 100.00% •: Struct<TestEnum, Data<alloc::vec::Vec<u8>>> 16 B 1.33% ⊢a: readme::main::TestEnum Lever ⊢ Variant: Unnamed 8 B 0.66% $\vdash 0:$ usize 1 B 0.08% [1: u8 [6B] Alloca get_s: 724 B 59.98% | -a: alloc::vec::Vec<u8> deep_: B 35.13% | ⊢b: alloc::vec::Vec<i32> 424 size_(35 B 2.90% mem_s: 1 B 0.08% ⊢0: u8 [7B] 27 B 2.24% 8 В 0.66% Lest: isize Additi

```
ons
.183 kB 98.01% ⊢b: readme::main::Data<alloc::vec::Vec<u8>>
                  L c: (u8, alloc::string::String)
                    └─1: alloc::string::String
```

By using the nightly offset_of_enum feature we can also display padding in enums

lower bound, but with operations asymptotically equivalent to standard structures

Succinct data structures: data structures using just the space of the information-theoretical

- lower bound, but with operations asymptotically equivalent to standard structures
- using log $4^n = 2n$ bits (Jacobson) instead of $2n \log n$

• Succinct data structures: data structures using just the space of the information-theoretical

- lower bound, but with operations asymptotically equivalent to standard structures
- using log $4^n = 2n$ bits (Jacobson) instead of $2n \log n$
- Partial port of sux (C++ project) and Sux4J (Java project)

• Succinct data structures: data structures using just the space of the information-theoretical

- lower bound, but with operations asymptotically equivalent to standard structures
- using log $4^n = 2n$ bits (Jacobson) instead of $2n \log n$
- Partial port of sux (C++ project) and Sux4J (Java project)
- There are some existing crates (some porting the projects above)

• Succinct data structures: data structures using just the space of the information-theoretical

- lower bound, but with operations asymptotically equivalent to standard structures
- using log $4^n = 2n$ bits (Jacobson) instead of $2n \log n$
- Partial port of sux (C++ project) and Sux4J (Java project)
- There are some existing crates (some porting the projects above)
- Rank and selection

• Succinct data structures: data structures using just the space of the information-theoretical

- lower bound, but with operations asymptotically equivalent to standard structures
- using log $4^n = 2n$ bits (Jacobson) instead of $2n \log n$
- Partial port of sux (C++ project) and Sux4J (Java project)
- There are some existing crates (some porting the projects above)
- Rank and selection
- Elias–Fano representation of monotone sequences (e.g., pointers into records)

• Succinct data structures: data structures using just the space of the information-theoretical

- lower bound, but with operations asymptotically equivalent to standard structures
- using log $4^n = 2n$ bits (Jacobson) instead of $2n \log n$
- Partial port of sux (C++ project) and Sux4J (Java project)
- There are some existing crates (some porting the projects above)
- Rank and selection
- Elias–Fano representation of monotone sequences (e.g., pointers into records)
- Sorted string compression by prefix omission

• Succinct data structures: data structures using just the space of the information-theoretical

- lower bound, but with operations asymptotically equivalent to standard structures
- using log $4^n = 2n$ bits (Jacobson) instead of $2n \log n$
- Partial port of sux (C++ project) and Sux4J (Java project)
- There are some existing crates (some porting the projects above)
- Rank and selection
- Elias–Fano representation of monotone sequences (e.g., pointers into records)
- Sorted string compression by prefix omission
- Fast bit vector and slices

• Succinct data structures: data structures using just the space of the information-theoretical

Mix-and-match of arbitrary rank and selection structures

- Mix-and-match of arbitrary rank and selection structures
- Functorial replacement of rank and selection structures (unsafe)

- Mix-and-match of arbitrary rank and selection structures
- Functorial replacement of rank and selection structures (unsafe)
- We use intensively the <u>ambassador</u> crate to delegate all rank, selection, and bit-vector access traits, so you can write

- Mix-and-match of arbitrary rank and selection structures
- Functorial replacement of rank and selection structures (unsafe)
- We use intensively the <u>ambassador</u> crate to delegate all rank, selection, and bit-vector access traits, so you can write

let bits = bit_vec![1, 0, 1, 1, 0, 1, 0, 1];let rank9 = Rank9::new(bits); let rank9_sel = SelectAdapt::new(rank9, 3);

- Mix-and-match of arbitrary rank and selection structures
- Functorial replacement of rank and selection structures (unsafe)
- We use intensively the <u>ambassador</u> crate to delegate all rank, selection, and bit-vector access traits, so you can write

let bits = bit_vec![1, 0, 1, 1, 0, 1, 0, 1];let rank9 = Rank9::new(bits); let rank9_sel = SelectAdapt::new(rank9, 3);

bit vector

• ... and the last structure has also rank methods and access to the underlying

Comprehensive set of traits for indexed dictionaries

- Comprehensive set of traits for indexed dictionaries
- Indexing, search, iteration, successor, predecessor, etc. in various forms

- Comprehensive set of traits for indexed dictionaries
- Indexing, search, iteration, successor, predecessor, etc. in various forms
- Presently, main implementation is Elias–Fano

- Comprehensive set of traits for indexed dictionaries
- Indexing, search, iteration, successor, predecessor, etc. in various forms
- Presently, main implementation is Elias–Fano
- Inner workings of the structure are selectable (or functorially modifiable)

- Comprehensive set of traits for indexed dictionaries
- Indexing, search, iteration, successor, predecessor, etc. in various forms
- Presently, main implementation is Elias–Fano
- Inner workings of the structure are selectable (or functorially modifiable)
- Also, compact string storage by prefix omission

- Comprehensive set of traits for indexed dictionaries
- Indexing, search, iteration, successor, predecessor, etc. in various forms
- Presently, main implementation is Elias–Fano
- Inner workings of the structure are selectable (or functorially modifiable)
- Also, compact string storage by prefix omission
- Main issue: lack of IndexGet or analogous trait makes access cumbersome

- Comprehensive set of traits for indexed dictionaries
- Indexing, search, iteration, successor, predecessor, etc. in various forms
- Presently, main implementation is Elias–Fano
- Inner workings of the structure are selectable (or functorially modifiable)
- Also, compact string storage by prefix omission
- Main issue: lack of IndexGet or analogous trait makes access cumbersome
- E.g., a functionally implemented vector that returns *i*² on index *i*

- Comprehensive set of traits for indexed dictionaries
- Indexing, search, iteration, successor, predecessor, etc. in various forms
- Presently, main implementation is Elias–Fano
- Inner workings of the structure are selectable (or functorially modifiable)
- Also, compact string storage by prefix omission
- Main issue: lack of IndexGet or analogous trait makes access cumbersome
- E.g., a functionally implemented vector that returns i² on index i
- Rust and intensional representations do not work very well together ATM

dsi-bitstream

• High-performance bit streams

- High-performance bit streams
- Read/write data by word (settable)

- High-performance bit streams
- Read/write data by word (settable)
- Supports little and big endian files

- High-performance bit streams
- Read/write data by word (settable)
- Supports little and big endian files
- Instantaneous codes for compression: Elias γ, Golomb, etc.

- High-performance bit streams
- Read/write data by word (settable)
- Supports little and big endian files
- Instantaneous codes for compression: Elias γ, Golomb, etc.
- tables or not?)

• Flexible architecture and benchmarks to tune to your hardware (use decoding)



- High-performance bit streams
- Read/write data by word (settable)
- Supports little and big endian files
- Instantaneous codes for compression: Elias γ, Golomb, etc.
- Flexible architecture and benchmarks to tune to your hardware (use decoding tables or not?)
- A γ code read in less than 2ns (for data with the intended distribution)



Basic traits: BitRead<E> / Bitwrite<E> (E is the endianness)

- Basic traits: BitRead<E> / Bitwrite<E> (E is the endianness)
- Extension traits like GammaRead / GammaWrite add code capabilities

- Basic traits: BitRead<E> / Bitwrite<E> (E is the endianness)
- Extension traits like GammaRead / GammaWrite add code capabilities
- Implementations BufBitReader<E, WR, RP> and BufBitWriter<E, WW, WP> depend on endianness and on the word size used to read or write data

- Basic traits: BitRead<E> / Bitwrite<E> (E is the endianness)
- Extension traits like GammaRead / GammaWrite add code capabilities
- Implementations BufBitReader<E, WR, RP> and BufBitWriter<E, WW, WP> depend on endianness and on the word size used to read or write data
- Moreover, the last parameter is a selector type that chooses whether to use encoding/decoding tables or not for each code

- Basic traits: BitRead<E> / Bitwrite<E> (E is the endianness)
- Extension traits like GammaRead / GammaWrite add code capabilities
- Implementations BufBitReader<E, WR, RP> and BufBitWriter<E, WW, WP> depend on endianness and on the word size used to read or write data
- Moreover, the last parameter is a selector type that chooses whether to use encoding/decoding tables or not for each code
- When reading, the internal bit buffer is twice the read word to make peeking possible (for tables)

- Basic traits: BitRead<E> / Bitwrite<E> (E is the endianness)
- Extension traits like GammaRead / GammaWrite add code capabilities
- Implementations BufBitReader<E, WR, RP> and BufBitWriter<E, WW, WP> depend on endianness and on the word size used to read or write data
- Moreover, the last parameter is a selector type that chooses whether to use encoding/decoding tables or not for each code
- When reading, the internal bit buffer is twice the read word to make peeking possible (for tables)
- Presently WR = u32 and WW = u64 are the best choice

Graph are represented by bitstreams

- Graph are represented by bitstreams
- Uses dsi-bitstream for instantaneous codes, sux for pointers into the bitstream

- Graph are represented by bitstreams
- Uses dsi-bitstream for instantaneous codes, sux for pointers into the bitstream
- visit is three time faster than Java (3h)

On a Software Heritage graph with 34 billion nodes and 517 billion arcs a BFS

- Graph are represented by bitstreams
- Uses dsi-bitstream for instantaneous codes, sux for pointers into the bitstream
- visit is three time faster than Java (3h)
- Unbelievably better ergonomics WRT Java

On a Software Heritage graph with 34 billion nodes and 517 billion arcs a BFS

- Graph are represented by bitstreams
- Uses dsi-bitstream for instantaneous codes, sux for pointers into the bitstream
- visit is three time faster than Java (3h)
- Unbelievably better ergonomics WRT Java
- Graphs have *n* nodes numbered in [0 . . *n*).

On a Software Heritage graph with 34 billion nodes and 517 billion arcs a BFS

- Graph are represented by bitstreams lacksquare
- Uses dsi-bitstream for instantaneous codes, sux for pointers into the bitstream
- visit is three time faster than Java (3h)
- Unbelievably better ergonomics WRT Java
- Graphs have *n* nodes numbered in [0 . . *n*).
- (usize) and a (possibly labeled) successor list (Intolterator<usize>)

On a Software Heritage graph with 34 billion nodes and 517 billion arcs a BFS

Access to the graph structure happens by enumerating pairs given by a node

Compression happens by several techniques:

- Compression happens by several techniques:
 - codes

• Gap compression: lists are turned into gaps encoded via instantaneous

- Compression happens by several techniques:
 - \bullet codes
 - Reference: lists are partially copied from other nodes with similar successors

Gap compression: lists are turned into gaps encoded via instantaneous

- Compression happens by several techniques:
 - codes
 - Reference: lists are partially copied from other nodes with similar successors
 - Intervalization: consecutive successors are stored as intervals

Gap compression: lists are turned into gaps encoded via instantaneous

- Compression happens by several techniques:
 - codes
 - Reference: lists are partially copied from other nodes with similar successors
 - Intervalization: consecutive successors are stored as intervals
- Composition-based labeling

Gap compression: lists are turned into gaps encoded via instantaneous

- Compression happens by several techniques:
 - codes
 - Reference: lists are partially copied from other nodes with similar successors
 - Intervalization: consecutive successors are stored as intervals lacksquare
- Composition-based labeling
- depending on the lender state

Gap compression: lists are turned into gaps encoded via instantaneous

Lender- (rather than Iterator-) based architecture, as we need to return items

 Permutation algorithms such as LLP provide node indices that improve compression significantly

- Permutation algorithms such as LLP provide node indices that improve compression significantly
- nodes are never materialized

Random-access enumeration of successor lists is lazy—lists of referenced

- Permutation algorithms such as LLP provide node indices that improve compression significantly
- Random-access enumeration of successor lists is lazy—lists of referenced nodes are never materialized
- Compact id space and lack of allocated structures to represent edges makes the framework applicable to very large graphs

- Permutation algorithms such as LLP provide node indices that improve compression significantly
- Random-access enumeration of successor lists is lazy—lists of referenced nodes are never materialized
- Compact id space and lack of allocated structures to represent edges makes the framework applicable to very large graphs
- An important change with respect to the Java version is that sequential enumeration of the arcs of a graph has no order guarantee

- Permutation algorithms such as LLP provide node indices that improve compression significantly
- Random-access enumeration of successor lists is lazy—lists of referenced nodes are never materialized
- Compact id space and lack of allocated structures to represent edges makes the framework applicable to very large graphs
- An important change with respect to the Java version is that sequential enumeration of the arcs of a graph has no order guarantee
- Though there are marker traits to request that

Basic trait: a SequentialLabeling

}

Basic trait: a SequentialLabeling

```
pub trait SequentialLabeling {
    type Label;
    type Lender<'node>:
    where
        Self: 'node;
```

```
fn num_nodes(&self) -> usize;
fn iter(&self) -> Self::Lender<'_>;
```

for<'next> NodeLabelsLender<'next, Label = Self::Label>

}

Basic trait: a SequentialLabeling

```
pub trait SequentialLabeling {
    type Label;
    type Lender<'node>:
    where
        Self: 'node;
    fn num_nodes(&self) -> usize;
    fn iter(&self) -> Self::Lender<'_>;
```

A sequential graph is a SequentialLabeling with usize labels

for<'next> NodeLabelsLender<'next, Label = Self::Label>

Random access:

• Random access:

pub trait RandomAccessLabeling: SequentialLabeling {
 type Labels<'succ>:
 IntoIterator<Item = <Self as SequentialLabeling>::Label>
 where
 Self: 'succ;

- Random access:
 - pub trait RandomAccessLabeling: SequentialLabeling { type Labels<'succ>: where Self: 'succ;
 - fn num_arcs(&self) -> u64; fn labels(&self, node_id: usize) -> <Self as RandomAccessLabeling>::Labels<'_>; fn outdegree(&self, node_id: usize) -> usize;
- A random-access graph is a RandomAccessLabeling with usize labels

IntoIterator<Item = <Self as SequentialLabeling>::Label>

Sabrina Jewson's idea)

• We use lenders based on higher-rank trait bounds (Lender crate, based on

- Sabrina Jewson's idea)

• We use lenders based on higher-rank trait bounds (Lender crate, based on

GAT-based lenders require the lender to be 'static, which is a no-no for us

- Sabrina Jewson's idea)

pub trait Lender { type Item<'this> where Self: 'a;

fn next(&mut self) -> Option<Self::Item<'_>>;

• We use lenders based on higher-rank trait bounds (Lender crate, based on

GAT-based lenders require the lender to be 'static, which is a no-no for us

- Sabrina Jewson's idea)

• We use lenders based on higher-rank trait bounds (Lender crate, based on

GAT-based lenders require the lender to be 'static, which is a no-no for us

- Sabrina Jewson's idea)

pub trait Lending<'a, __ImplBound = &'a Self> { type Lend: 'a; }

pub trait Lender: for<'a /* where Self: 'a */> Lending<'a> { fn next(&mut self) -> Option<<Self as Lending<'_>::Lend>;

• We use lenders based on higher-rank trait bounds (Lender crate, based on

• GAT-based lenders require the lender to be 'static, which is a no-no for us

• This not enough for us

- This not enough for us
- state of the lender

• For example, when iterating over a graph obtained by sorting source/target pairs (e.g., a transpose), we need the iterator on successors to modify the

- This not enough for us
- state of the lender
- Suggestion by quinedot on the Rust Language Forum:

• For example, when iterating over a graph obtained by sorting source/target pairs (e.g., a transpose), we need the iterator on successors to modify the

- This not enough for us
- state of the lender
- Suggestion by quinedot on the Rust Language Forum:
- pub trait NodeLabelsLender<'a, __ImplBound = &'a Self>: Lender + Lending<'a, __ImplBound, Lend = (usize, Self::IntoIterator)> type Label; type IntoIterator: IntoIterator<Item = Self::Label>;

• For example, when iterating over a graph obtained by sorting source/target pairs (e.g., a transpose), we need the iterator on successors to modify the



Performance

Graph	Nodes	Arcs	Avg. Degree	b/arc	Size (comp.)
dblp-2010	326K	1.6M	4.95	6.78	1.4MB
hollywood-2011	2M	229M	105.00	4.89	140MB
enwiki-2023	4.2M	101M	24.93	13.55	267MB
in-2004	41M	1.1G	27.87	1.41	250MB
webbase-2001	118M	1G	8.63	2.78	399MB
twitter-2010	41M	1.4G	35.25	13.90	2.5GB
eu-2015	1G	92G	85.74	1.19	13GB
swh-2023	34G	491G	14.38	3.07	176GB



dblp-

holly

enwi

in-20

webt

twitte

eu-20

swh-

	Java	Rust	speedup	Java	Rust	speedup	
ph	Random access (ns/arc)			BFS visit (ns/node)			
o-2010	96	50	× 1.92	604	220	× 2.75	
ywood-2011	51	27	× 1.88	7520	2620	× 2.87	
/iki-2023	61	31	× 1.97	1450	734	× 1.98	
004	70	37	× 1.89	735	369	× 1.99	
base-2001	114	73	× 1.56	665	322	× 2.07	
ter-2010	73	38	× 1.92	2650	1270	× 2.09	
2015	24	17	× 1.41	1580	971	× 1.63	
า-2023	104	47	× 2.21	1140	359	× 3.18	

• This journey started in April 2023 and it has been a blast

- This journey started in April 2023 and it has been a blast
- improve the design and implementation of a codebase that had been accumulating for 20 years

• It was very surprising for me that we were able to port and, in fact, massively

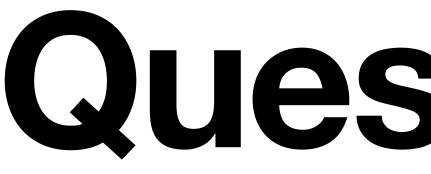
- This journey started in April 2023 and it has been a blast
- improve the design and implementation of a codebase that had been accumulating for 20 years
- Graph traversals, graph algorithms, etc., are on their way

• It was very surprising for me that we were able to port and, in fact, massively

- This journey started in April 2023 and it has been a blast
- It was very surprising for me that we were able to port and, in fact, massively improve the design and implementation of a codebase that had been accumulating for 20 years
- Graph traversals, graph algorithms, etc., are on their way
- We would like to thank Valentin Lorentz at Software Heritage for a lot of improvements and suggestions (and for being our guinea pig)

- This journey started in April 2023 and it has been a blast
- It was very surprising for me that we were able to port and, in fact, massively improve the design and implementation of a codebase that had been accumulating for 20 years
- Graph traversals, graph algorithms, etc., are on their way
- We would like to thank Valentin Lorentz at Software Heritage for a lot of improvements and suggestions (and for being our guinea pig)
- And we would like to thank the community of the Rust Language Forum, without which none of this would have ever happened

- This journey started in April 2023 and it has been a blast
- It was very surprising for me that we were able to port and, in fact, massively improve the design and implementation of a codebase that had been accumulating for 20 years
- Graph traversals, graph algorithms, etc., are on their way
- We would like to thank Valentin Lorentz at Software Heritage for a lot of improvements and suggestions (and for being our guinea pig)
- And we would like to thank the community of the Rust Language Forum, without which none of this would have ever happened
- And my students, without whom we would be far behind schedule



Questions?